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this book introduces a unifying framework for the study of open, underwater, and surface environment systems with available vibration/motion/pressure/temperature sensors. a mathematical modeling approach is developed to represent the nonlinear physical properties of underwater robots in fully coupled and uncoupled forms. by using the state-space and adaptive design techniques, the corresponding state-feedback control schemes are developed to make the robot achieve its required performance specifications. nonlinear control strategies for different modes are investigated, and a joint control strategy is proposed for stabilizing the multiple-axis robot. the book introduces the all digital circuit as a general circuit for building of wireless sensors and actuators. the book deals with basic topics like circuit theory, basic circuit analysis, and the design of all digital circuits and systems. topics covered are comparators, differential amplifiers, op-amps, linear filters, voltage and current operational amplifiers, operational amplifiers, and simple control systems. the book is designed to cover all the concepts of digital circuit from the basic level to the advanced level. the aim of this book is to build a foundation for a subject that requires elements of many fields of study. the book will give you a basic knowledge about digital electronics, and help you to build an awareness about the complexities involved in its design. this book covers the following topics under the curriculum of class xi and class xii: systematic botany systematic zoology (swann flora) general botany general zoology phycology landscape ecology environmental issues habitat and its importance introduction to community ecology and introduction to environmental research.

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